

Threads in user space

↳ create (TCB + stack + g)

↳ yield (to switch threads)

↳ not a `goto`

f1() { ∞ loop }

f2() { ∞ loop }

main

{ fork → call f1

f2

}

← separate process runs

f1

How to we implement threads?

→ need thread control blocks

→ need context switches

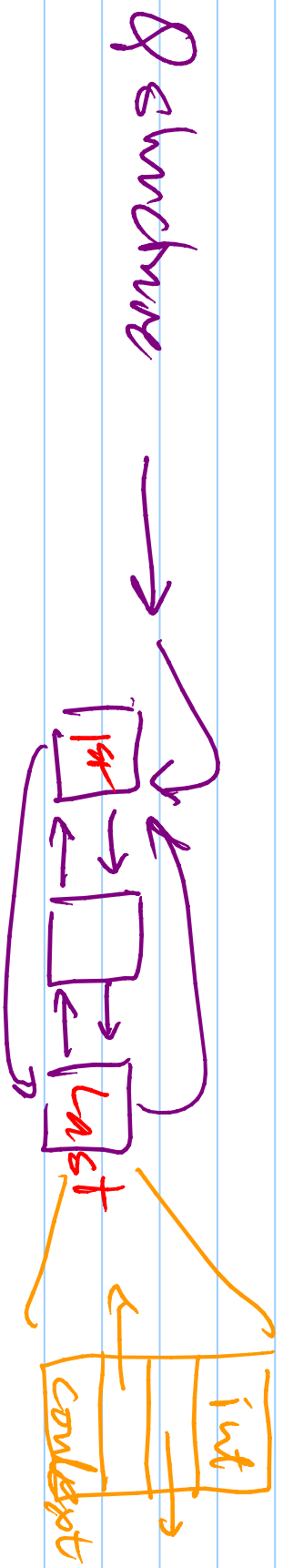
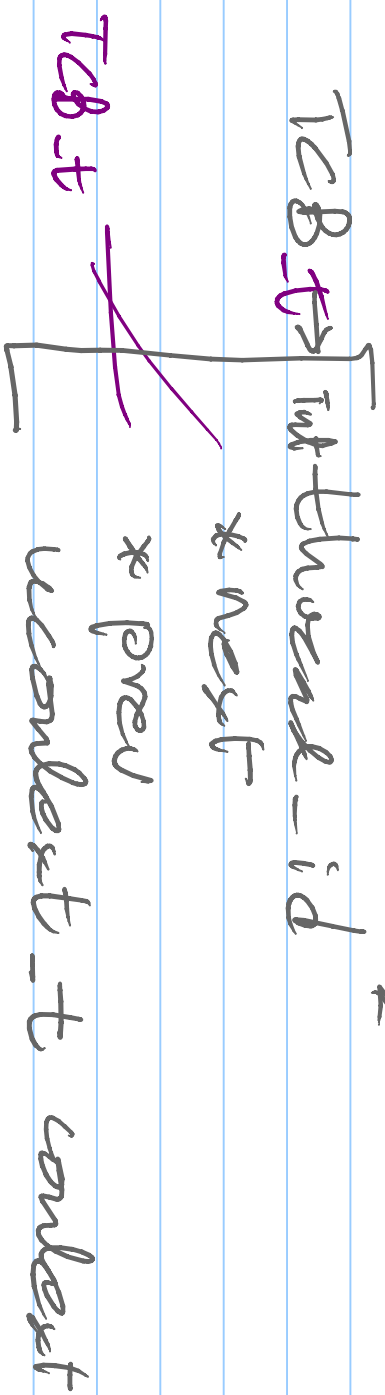
↓
_ hardware dependencies

- need assembly

library

- `recontext_t` → a type (struct) that stores a thread context
- `makecontext()` } call to init TCBs
→ `getcontext()`
- `swapcontext (from, to)` switch

Need a TCB ← struct



initQ(Q)

AddQ(Q, element)

element = DelQ(Q)

works on
multiple

Qs

RotateQ(Q) = AddQ(Q, DelQ(Q));

// done by moving
the header

to start a thread $\rightarrow$ for function f

- allocate a TCB (malloc)

- allocate a stack (malloc)

$\hookrightarrow$... size? 8k

- INIT TCB $\rightarrow$ complicated

(code provided) $\rightarrow$ was $\rightarrow$ makecontext()

$\textcircled{f}$

Global pointer

StartThread(f)

{

allocate

→ TCB & stack

make context (f)

AddQ(RunQ, TCB)

}

yield()

{ curr = runq;

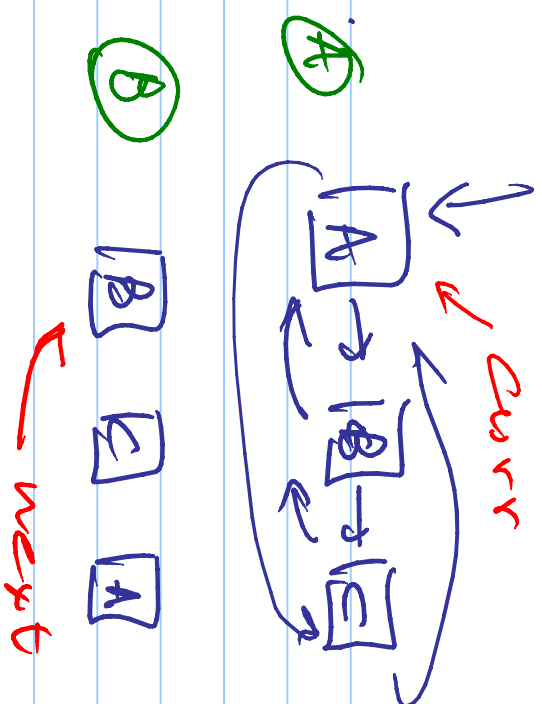
Rotateq (Runq);

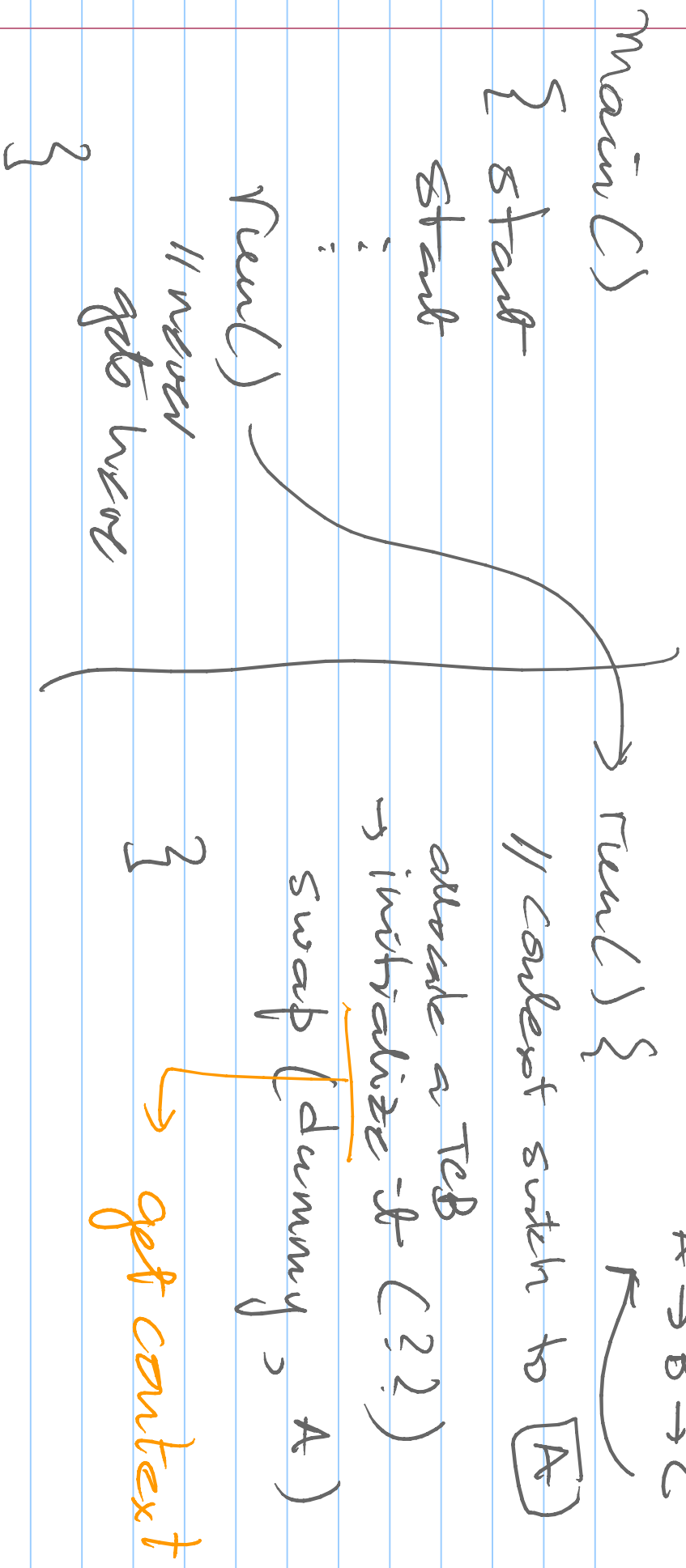
next = Runq

Swap context (curr → context,

next → context)

}





yield() $\rightarrow$ ① what if Run 8
has 1 TCB?

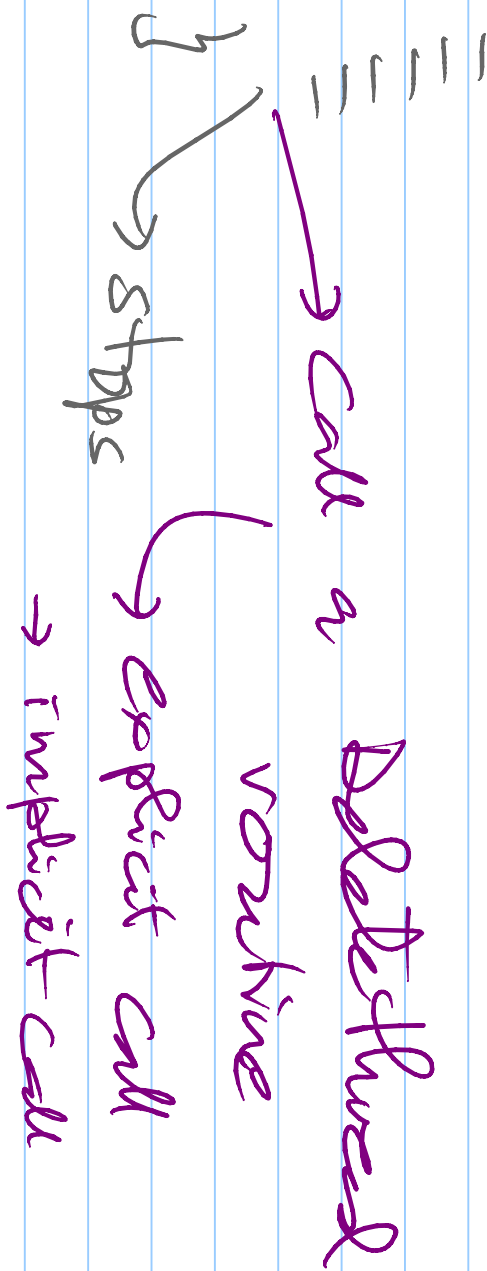
== $\rightarrow$ thread continues

② $\gg$ Run 8 has 0 TCB

$\rightarrow$ add an ~~id~~ idle process $\rightarrow$

Can a thread terminate?

$f1(c) \{ \rightarrow \text{start it}$



RunQ is empty

→ run idle process / thread

→ terminate

→ return to main

↳ need to have the

"dummy" TCB

main() {

Start
Start

...

main()

→ never returns

→ return if
all threads
terminate

→ returns immediately

main becomes a
thread

put
dummy
into runs
& then swap context

main()

{ start

start

run

→ swap

→ create a context
for this thread
→ put in RunQ

} → this part
will run.

} ← exit

Another look at swapcount

yield()

```
{  
    swap(f, t) } swap(f, t)  
    { move vgs → f  
      move sp → f  
      move t → vgs  
      move t → sp  
    }  
    RET  
}
```

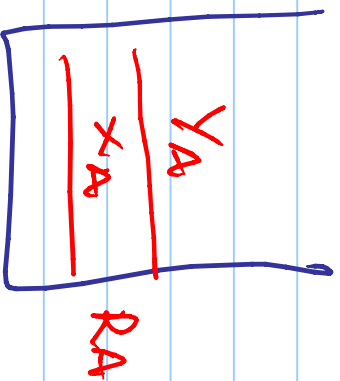
Thread A

①

③

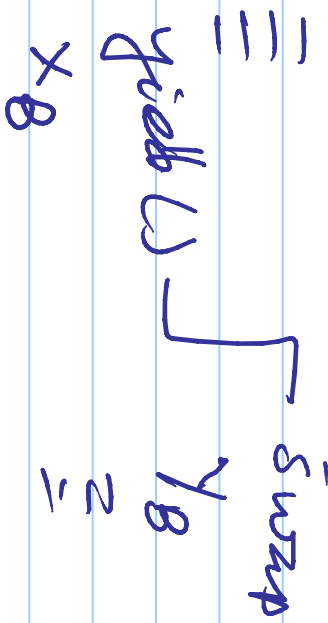


Stack A

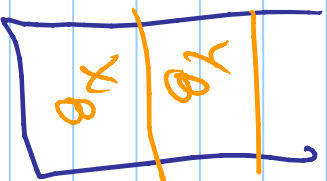


Thread B

②



Stack B



- User level scheduling

- non preemptive (need yield)
- execution is atomic
 - ↳ critical sections for
proc
- explicit yields are NOT needed

kernel level scheduling

- Thread creation → kernel
- call → PCB stored in kernel
- yield → kernel call
 - ↳ also called by timer int

→